#### Automated Micro-analysis of Haskell

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#### Overview

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#### Background

Andrew Shewmaker worked on a project performing micro-analysis of C[1]. Approach was probabilistic, recommended solving recurrence equations.

Not much research on static execution time analysis of Haskell.

### Assumptions

- Simplified syntax
- Time functions are exact polynomials
- Function arguments are integers or lists
- Time function only depends on list length
- Compiler is non-optimizing
- Arguments and results are fully evaluted

## Generating Recurrence Equations

For example, consider a factorial function:

$$fac 0 = 1$$

$$fac x = \underbrace{x * fac(x - 1)}_{T_{fac}(x-1)}$$

The recurrence equations would be:

$$T_{fac}(0) = 1$$
 $T_{fac}(x) = 7 + T_{fac}(x - 1)$ 

# Substitute Polynomial for Time Function

Assuming 
$$T_{fac}(x) = ax^2 + bx + c$$
, we get: 
$$a0^2 + b0 + c = 1$$
 
$$ax^2 + bx + c = 7 + a(x - 1)^2 + b(x - 1) + c$$

## Create Linear System of Polynomial Coefficients

The previous equations simplify to:

$$c = 1$$
$$0 = 7 - 2ax + a - b$$

The linear system extracted from this is:

$$c = 1$$
  
 $0 = -2a$   
 $0 = 7 + a - b$ 

## Solve Linear System

The linear system can be expressed as:

$$\begin{bmatrix} 0 & 0 & 1 \\ 2 & 0 & 0 \\ -1 & 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 7 \end{bmatrix}$$

Solving this yields a=0, b=7, and c=1, so the final solution is  $T_{fac}(x)=7x+1$ .

## More Examples

```
-- Should be 5/2*x^2 + 15/2*x + 5y + 2
f5 \ 0 \ 0 = 0
f5 \times 0 = f5 (x-1) \times
f5 \times y = f5 \times (y-1)
-- Should be 7x + 1
f6x =
    case x of
       0 -> 0
       y \rightarrow 1 + f6 (y - 1)
-- Should be 4x + 1
f7 :: [Int] -> Int
f7 \mid 1 = 0
f7 (x:xs) = 1 + f7 xs
```

## **Under-constrained System**

The linear system may be under-constrained (e.g. a-b=0). This may be caused by lack of a base case.

$$fac x = x * fac(x - 1)$$
 
$$T_{fac}(x) = 7 + T_{fac}(x - 1)$$
 
$$ax^{2} + bx + c = 7 + a(x - 1)^{2} + b(x - 1) + c$$

In this case, c is undetermined.

#### Over-constrained System

The linear system may be over-constrained (e.g. a=0 and a=1)

- Time function may not be a polynomial
- Time function may have multiple cases
- Polynomial may have a higher degree than what was used

#### Conclusion

- Porting code from Java to Haskell is hard
- Monads are useful
- Haskell's unique features make it interesting to analyze
  - Easy immutability, no side effects
  - Hard lazy evaluation
- Difficult problem
- Lots of room for improvement
  - More supported syntax
  - Asymptotic time (esp. for partially solved systems)
  - Non-polynomial time functions
  - Verification; execution time as API

#### References



Andrew Shewmaker.

Micro-analysis of C project report.

http://users.soe.ucsc.edu/~cormac/wiki/lib/exe/fetch.php?id=projects&cache=cache&media=micro-analysis-of-c-report.pdf, Dec 2007.